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**Description**

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**Modular printing unit**

The invention relates to a printing unit for printing webs.

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The object of the invention is to provide a printing unit which is designed with the lowest possible expenditure on construction and high flexibility.

15 The object is achieved according to the invention by the features of patent claim 1.

The modular printing unit advantageously comprises three main groups:

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- a frame, which performs the load-bearing function and accommodates all the services and operating elements, alternatively a stand configured in the manner of a frame can also be used,

- 25
- format-independent "subunits" which are mounted in the frame or stand and which contain the auxiliary subassemblies necessary to the printing process. In the offset process which is common nowadays, these are mainly inking and damping units,

- 30
- at least one crossmember which is configured as a "locking bar", which is arranged in the frame or connected to the stand on both sides and in which the main subassemblies necessary for printing - plate cylinders and rubber-covered cylinders in offset printing - are mounted.
- 35

In addition, additional equipment such as plate loading systems or digital imaging systems (direct imaging) can be mounted in the crossmember.

Each crossmember is equipped with one or more swinging arms for what are known as the printing mechanisms, in order to pivot the rubber-covered cylinders.

5 A great advantage of this system is the independence of the printing process, so that adaptations to the future innovations are possible at any time by replacing the corresponding subassemblies. In addition, the  
10 fundamental change or adaptation to other printing processes and to all varieties of offset printing can be covered. By means of the appropriate adaptation of the subunits and/or the crossmember, the printing unit can be extended or converted to anilox, dry offset printing, gravure printing or any printing process  
15 developed in the future, with its preconditions.

A modular printing unit configured as an H printing unit can be equipped with 1, 2, 3, 4 or more printing points, a modular printing unit configured as an I  
20 printing unit with 1, 2 or more printing points. In the I design, imprinting mechanisms can also be installed as a result. The subunits of the modular printing unit are preassembled for this purpose and are attached to the frame.

25 The ratio of the plate cylinders to rubber-covered cylinders mounted in the crossmember can be  $x:x$  or  $x:y$  (for  $y > x$ ), but advantageously 1:1, 1:2 and 2:2. However, 2:3, 3:3 and so on are just as conceivable.

30 The proportion of the wall for inking and damping units is separate from the proportion of the wall for plate cylinders and rubber-covered cylinders and is called a "subunit" here. The inking units can alternatively  
35 contain 1, 2, 3 or 4 and more ink applicator rolls and as many distributor cylinders as desired. The damping units can alternatively contain 1 or 2 damping solution transfer rolls and as many distributor cylinders as desired. Inking and damping units can also be

connected to one or more "coupling rolls" for indirect damping.

5 The rubber-covered cylinder is pivoted out by means of  
a swinging arm arranged in the crossmember for good  
accessibility (for example replacement of the rubber-  
covered cylinder cover, removal of a wrap); the pivot  
for this purpose is advantageously located at the  
center of the plate cylinder. Translational movements  
10 are not absolutely necessary but there is the  
possibility of displacing the impression cylinder,  
rubber-covered cylinder and plate cylinder arranged in  
the crossmember in the translational direction in  
relation to one another.

15 The subunits are designed in a modular way, which are  
advantageously constructed identically, these primarily  
accommodating inking and damping units. As a result of  
the identical structure of the subunits, these can  
20 advantageously be given the same dimensions, which  
improves the replaceability and minimizes the  
production costs.

From this, in the case of identical subunits, it is  
25 possible to derive

- a) H printing units with identical height and, if  
appropriate, format-dependent different width with  
a horizontal crossmember and
- 30 b) I printing units with identical widths and, if  
appropriate, format-dependent different height  
with vertical crossmember.

By means of the combination of a top left and bottom  
35 right subunit designed in a modular way, it is possible  
to construct an I printing unit for a left-right  
machine; by means of the combination of a top right and  
bottom left subunit designed in a modular way, it is

possible to construct an I printing unit for a right-left machine.

5 The cylinders for plate cylinders and rubber-covered cylinders can be arranged in the crossmember flat, that is to say in one line, crossed in any direction or arranged at angles to one another.

10 The modular printing unit can be equipped with various types of drive:

- H drive for the simultaneous drive of four printing mechanisms, integrated in the frame
- bridge drive for the simultaneous drive of two printing mechanisms, integrated in the crossmember, advantageously positioned at the center of the plate cylinder and driving the rubber-covered cylinder via drive elements
- individual drive for each printing mechanism, integrated in the crossmember, advantageously positioned at the center of the plate cylinder and driving the rubber-covered cylinder via drive elements, or integrated in the respective subunit.

25 In order to throw the print on and off, plate cylinder and rubber-covered cylinder can be moved toward each other via eccentrics.

30 The frames, crossmembers and swinging arms can be created constructionally simply and, as a result, cost-effectively. For example, the crossmembers can be implemented with commercially available profiles. In addition, the printing units configured by means of the frame, the crossmembers and the swinging arms are distinguished by a reduced-weight, compact and space-saving design.

35 Thus, using one and the same printing unit, it is possible to print as desired in the gravure printing or offset printing process, it being possible for the

machine to be converted simply from one process to the other as a result of the modular design and the replacement of the crossmember fitted with the appropriate cylinders and the replacement of the  
5 corresponding modular subunits. In addition, both printing processes can be used simultaneously. Furthermore, for example the one printing process can be used for the recto printing and the other printing process can be used for the verso printing. The press  
10 manufacturer can create the machines for both processes identically from the same components, which permits cost-effective fabrication. In addition, the printing devices can be designed with variable format, that is to say they can be converted simply to other formats,  
15 i.e. other diameters of the printing mechanism cylinders and section lengths. Moreover, the printing unit can be changed over quickly to different production variants. Furthermore, the printing unit can also be converted to a varnishing unit or at least  
20 as a varnishing mechanism for recto printing or for verso printing.

It is significant that a printing unit of modular design is provided for printing webs, which has a stand  
25 which is provided with at least one crossmember at both ends (drive side and operating side), printing cylinders being mounted in the crossmembers in such a way that a structural unit comprising crossmembers and printing cylinders can be taken completely out of and  
30 put into the stand.

Further features and advantages emerge from the subclaims in conjunction with the description.

35 The invention is to be explained in more detail in the following text by using some exemplary embodiments. In the drawings, in schematic form:

fig. 1 shows a printing unit according to the invention, configured as an H printing unit having four printing points,

5 fig. 2 shows a drive of a printing mechanism according to fig. 1,

fig. 3 shows a further drive of a printing mechanism according to fig. 1,

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fig. 4 shows a printing unit according to the invention configured as an I printing unit,

15 fig. 5 shows an illustration of the subunits in the case of different formats.

Figure 1 shows a printing unit 1 of a web-fed rotary press, comprising a stand 2 constructed in the manner of a frame having two crossmembers 3; 4 to be connected to the latter on both sides, in each case two printing mechanisms 5 to 8 having plate cylinders 9 to 12 and rubber-covered cylinders 13 to 16 being arranged in the crossmembers 3; 4 and the crossmembers 3; 4 being arranged horizontally in the stand 2. The plate cylinders 9 to 12 and the rubber-covered cylinders 13 to 16 are here arranged in line in the crossmember 3; 4. They can be arranged in the crossmember 3; 4 crossed in any direction or at angles to one another, not illustrated here. Each printing mechanism 5 to 8 or each plate cylinder 9 to 12 is connected to a subunit 17 to 20 of modular design, the subunit 17 to 20 being arranged between the respective crossmember 3; 4 and the stand 2. Inking and damping units, not specifically illustrated, are integrated in the subunits 17 to 20.

The printing unit 1 equipped with four printing mechanisms 5 to 8 in this way represents what is known as an H printing unit with four printing points, a web 29 to be printed being led through between the rubber-

covered cylinders 13 to 16. The printing mechanisms 5 to 8 print the web 29 on both sides.

Alternatively, the rubber-covered cylinder 13; 15 or the rubber-covered cylinder 14; 16 can be configured as an impression cylinder 50, the respective form cylinder 9 to 12 belonging to the rubber-covered cylinder 13 to 16 now designed as an impression cylinder 42 being omitted. The web 29 is thus printed on one side.

The respective rubber-covered cylinder 13 to 16 can be pivoted on the crossmember 3; 4 by means of a swinging arm 21 to 24, the pivot of the swinging arm 21 to 24 preferably being an axle 25 to 28 of the respective plate cylinder 9 to 12. The crossmember 3; 4 is screwed to the stand 2 on both sides (not specifically illustrated), so that, for example, replacement of the respective printing mechanisms 5 to 8 can be effected quickly.

The crossmember 3; 4 consists, for example, of sheet metal turned over at the edge or sheet metal profiles. The printing cylinders 9 to 16 can be moved in relation to each other via bearing points configured as eccentrics in order to throw the print on/off.

Figure 2 shows a drive 30 of the printing mechanism 5. The drive 30 comprises a drive motor 31 which has a drive connection to the plate cylinder 9 via a clutch 32. The plate cylinder 9 is connected to the rubber-covered cylinder 13 via gears 33; 34 arranged on their axles 25; 35. The drive motor 31 is arranged on a bracket 36 connected to the crossmember 3. Mounted on the axle 25 of the plate cylinder 9 is the swinging arm 21, which can be pivoted about the axle 25 by means of a pivoting motor 38 which is fixed to the bracket 36 and engages with a toothed segment 37 arranged on the swinging arm 21. Before the pivoting action, a locking device 39 has to be released which, during printing operation, connects the swinging arm 21 to the bracket

36 in a locking manner. It is self-evident that the crossmember 3 is equipped with a cutout 40 along the pivoting travel of the axle 35 of the rubber-covered cylinder 13. Although not specifically illustrated, the swinging arm 21 can also be pivoted by means of an operating cylinder operated by pressure medium instead of by means of the pivoting motor.

Figure 3 shows a variant of figure 2. Here, the drive motor 31 drives the rubber-covered cylinder 13 for example via a drive element 41, for example a toothed belt. In a manner analogous to fig. 2, the drive motor 31 is located in its position at the center  $M_p$  of the plate cylinder 9, in order that it does not change its position when the rubber-covered cylinder 13 is pivoted out.

Figure 4 shows a printing unit 50 which is configured as an I printing unit. In an I printing unit 50, the crossmember 51 is, for example, configured in the shape of a T and the web 29 is led through the printing unit 50 in the horizontal direction. The I printing unit 50 can be equipped with 1 or 2 printing points. Thus, imprinting mechanisms can also be incorporated in an I design. The subunits 52; 53 are preassembled in a way analogous to fig. 1 for this purpose and are fitted in the stand 54.

By means of the combination of a top left 52 and bottom right subunit 53 designed in a modular way, it is possible to construct an I printing unit 50 for a left-right machine (see fig. 4, upper illustration); by means of the combination of a top right 55 and bottom left subunit 56 designed in a modular way, it is possible to construct an I printing unit 50 for a right-left machine (see fig. 4, lower illustration).

The subunits 17 to 20 are shown in figure 5. The subunits 17 to 20 always have the same dimensions, it being possible for the stands 2; 2' to be different in



their format or in their dimensions, the dimension and the format of the stands 2; 2' depending on the number and dimension of the printing cylinders used. While viewing the two illustrations shown in figure 5, it is possible to see the identically dimensioned subunits 17 to 20, but with the format difference between the stands 2; 2' represented by  $\Delta B$ .

# Designations

1	Printing unit	33	Gear
2; 2'	Stand	34	Gear
3	Crossmember	35	Axle
4	Crossmember	36	Bracket
5	Printing mechanism	37	Toothed segment
6	Printing mechanism	38	Pivoting motor
7	Printing mechanism	39	Locking device
8	Printing mechanism	40	Cutout
9	Plate cylinder	41	Drive element
10	Plate cylinder	42	Impression cylinder
11	Plate cylinder		
12	Plate cylinder	43	
13	Rubber-covered cylinder	44	
		45	
14	Rubber-covered cylinder	46	
		47	
15	Rubber-covered cylinder	48	
		49	
16	Rubber-covered cylinder	50	Printing unit
		51	Crossmember
17	Subunit	52	Subunit
18	Subunit	53	Subunit
19	Subunit	54	Stand
20	Subunit	55	Subunit
21	Swinging arm	56	Subunit
22	Swinging arm	57	
23	Swinging arm	58	
24	Swinging arm	59	
25	Axle	60	
26	Axle	61	
27	Axle	62	
28	Axle	$M_P$	Center of plate cylinder
29	Web		
30	Drive	$\Delta B$	Difference in format
31	Drive motor		
32	Clutch		